CONSERVATION LAWS AND SIMILARITY REDUCTION OF THE ZOOMERON EQUATION

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In this study, we consider a 4-th order (1+1)-dimensional PDE called Zoomeron equation. Some conservation laws are derived based on direct method. We also derived some similarity solutions using the symmetries.

Key words: Zoomeron equation, Lie point symmetries, conservation laws, multiplier, similarity solution.

Introduction

The Zoomeron equation is a 4-th order non-linear single PDE in the form of:

\[
\left( \frac{u_{xt}}{u} \right)_{tt} - \left( \frac{u_{xt}}{u} \right)_{xx} + 2(u^2)_{xt} = 0. \tag{1}
\]

In the study of DEs, conservation laws play significant roles not only in obtaining in-depth understanding of physical properties of various systems, but also in constructing of their exact solutions. They described physical conserved quantities such as mass, energy, momentum and angular momentum, as well as charge and other constant of motion. They are important for investigating integrability and linearization mapping and for establishing existence and uniqueness of solutions. They are also used in the analysis of stability and global behaviour of solutions. In addition they play an essential role in the development of numerical methods and provide an essential starting point for find non-locally related systems and potential variables. Moreover, the structure of conservation laws is coordinate-free, as a point or contact transformation maps a conservation laws into a conservation laws. A systematic way of constructing the conservation laws of a system of DEs that admits a variational principle is via Noether’s theorem. Its application allows physicists to gain powerful insights into any general theory in physics just by analyzing the various transformations that would make the form of the laws involved invariant. For instance, the invariant of physical systems with respect to spatial translation, rotation and time translation respectively give rise to the well known conservation laws of linear momentum, angular momentum and energy.

Among the generalization of Noether’s theorem an Ibragimov’s theorem \[9\], based on the self-adjointness of DEs allows to find independent conservation laws for a system of PDEs. This method is very limited because of the self-adjointness. But the direct method has no any limitation and is applicable for any system of DEs. Thus, in this paper we use the second method for finding some conservation laws for the Eq. (1). The objective of this article is to look for conservation laws and exact solutions for solving the (1+1)-dimensional Zoomeron equation, where \(u(x,t)\) is the amplitude of the relevant wave mode. This equation is one of incognito equation. According to our recent search, there are a few article about this equation. We only know that this equation was introduced by Calogero and Degasperis \[1, 4, 5\].

The paper is organized in the following manner. In section 2 the conservation laws of the Zoomeron equation are obtained in direct method and were expressed in section 3 similarity reductions and explicit solutions.

The direct method for construction of coservation laws

In general, non-trivial local conservation laws arise obtain from linear combinations of the equations of the PDEs system with multipliers that yield non-trivial divergence expressions. In asking such expressions, the dependent variables and each of their derivatives that arise in PDEs system, or appear in the multipliers, are replaced by arbitrary functions \[2, 8\]. By their construction, such divergence expressions vanish on all solutions of the PDEs system. In particular, a set of multipliers \(\{\xi_\sigma[U]\}_{\sigma=1}^{N} = \{\xi(x,U,\partial U,\cdots, \partial^j U)\}_{\sigma=1}^{N} \) yields a divergence expressions for PDEs system \(R\{x;u\}\) if the identity

\[
\xi_\sigma[U]R^\sigma[U] = D_i\Phi^i[U], \tag{2}
\]
holds for arbitrary functions $U(x)$.

A set of non-singular local multipliers \( \{ \xi^\sigma(x,U,\partial U,\cdots,\partial^kU)\}_{\sigma=1}^N \) yields a local conservation law for the PDEs system $R\{x,u\}$ if and only if the set of identities,

\[
E_{U\ell}(\xi(x,U,\partial U,\cdots,\partial^lU)R^\sigma(x,U,\partial U,\cdots,\partial^kU)) = 0
\]

holds for arbitrary functions $U(x)$.

We apply this method to obtain the local conservation laws of Eq. (1). Let

\[
R[u] = u^2u_{ttt} - uu_{tt}u_{xt} - 2uu_{tt}u_{xt} + 2u^2u_{xt} - u^2u_{xxx} + uu_{xxt}u_{xt} + 2uu_{xxt}u_{xt} - 2u^2u_{xtt} + 4uu_{u}u^3 + 4u^4u_{xt}.
\]

In the following manner we explain the calculations to find the multipliers and local conservation laws. First we search all local conservation law multipliers of the form zero order

\[
\xi = \xi(x,t,U),
\]

for the Eq. (4). Using the Euler operators

\[
E_U = \frac{\partial}{\partial U} - D_t\frac{\partial}{\partial U_t} - D_x\frac{\partial}{\partial U_x} + D_{xt}\frac{\partial}{\partial U_{xt}} + D_{xxt}\frac{\partial}{\partial U_{xxt}} - D_{xxtt}\frac{\partial}{\partial U_{xxtt}},
\]

the determining equations (3) for the multipliers (4) becomes:

\[
E_U[\xi(x,t,U)(U^2U_{xtt} - UU_tU_{xt} - 2UU_tU_{xt} + 2U^2U_{xt} - U^2U_{xxx} + UU_{xxt}U_{xt} + 2UU_{xxt}U_{xt} - 2U^2U_{xtt} + 4UU_{u}U^3 + 4U^4U_{xt})] = 0,
\]

where $U(x,t)$ are arbitrary functions. Equations (7) split with respect to each of dependent variables derivatives that arise in PDEs system (except dependent variables) such as $U_t$, $U_x$, $U_{xx}$, $U_{xt}$, $U_{xxt}$, to yield the over-determined linear PDEs system given by (8).

\[
\text{zeroth characteristic} = \left\{ \begin{array}{l}
U_t = 12\xi_tU^3 + 4\xi_{xt}U^4 + 8\xi_{xtt}U + 3\xi_{xxt}U^2 - 2\xi_{xxx}U = 0, \\
U_{xt} = 24\xi_tU^3 + 8\xi_{xt}U^4 - 7\xi_{xtt}U + 7\xi_{xxt}U + 3\xi_{xxtt}U^2 - 3\xi_{xxx}U^2 = 0, \\
\vdots \\
U_{xxtt} = 2\xi_tU^2 + 6\xi U = 0.
\end{array} \right.
\]

The solution of (8) are the four sets of local multipliers given by (9),

\[
\xi_1(x,t,u) = \frac{1}{u^3}, \quad \xi_2(x,t,u) = \frac{t}{u^3}, \quad \xi_3(x,t,u) = \frac{x}{u^3}, \quad \xi_4(x,t,u) = \frac{t^2 + x^2}{2u^3}.
\]

Similarly each $\xi$ determines a non-trivial zeroth order local conservation law $D_t\Psi(x,t,U) + D_x\Phi(x,t,U) = 0$, with the characteristic from

\[
\xi(x,t,U)R[U] = D_t\Psi(x,t,U) + D_x\Phi(x,t,U).
\]
We can find after placement (11) in (14) and doing some tedious calculations table (2) is obtained. Now we search all local conservation law multipliers of the form first order, 

\[ \xi = \xi(x,t,U,U_x,U_t), \]  

(11)

for the Eq. (4). Using the corresponding Euler operators the determining equations (3) for the multipliers (4) become:

\[ E_U \left[ \xi(x,t,U,U_x,U_t)(U^2U_{xxt} -UU_{tt}U_{xt} -2UU_tU_{xt} +2U_t^2U_{xt} -U^2U_{xxxt} +UU_{xx}U_{xt} +2UU_xU_{xxt} -2U_x^2U_{xt} +4U_xU_xU^3 +4U^4U_{xxt}) \right] = 0. \]

(12)

Equations (12) split with respect to each of dependent variables derivatives that arise in PDEs system (except dependent variables and first order derivatives of them) such as \( U_{xx}, U_{tt}, U_{xt}, U_{xxt}, \ldots \) to yield the over-determined linear PDEs system given by (13).

\[
\text{first characteristic} = \begin{cases} 
  U_{xxt} & -\xi U_{tt} = 0, \\
  U_{tt} & -\xi U_x -UU_x \xi U = 0, \\
  \vdots & \vdots \\
  U_{xxt} & 2\xi U_{x}U_{U_t} -3U^2U_x \xi U_{U_t} -3U^2\xi U_{U_t} = 0.
\end{cases}
\]

(13)

The solution of (13) (\( \xi(x,t,U,U_x,U_t) \)) are the same as given by, (9). Each \( \xi(x,t,U,U_x,U_t) \) determines a non-trivial first order local conservation law \( D_t\Phi(x,t,U,U_x,U_t) +D_x\Phi(x,t,U,U_x,U_t) = 0 \), with the characteristic from

\[ \xi(x,t,U,U_x,U_t)R[U] = D_t\Psi(x,t,U,U_x,U_t) +D_x\Phi(x,t,U,U_x,U_t). \]

(14)

After placement (11) in (14) and doing some tedious calculations table (2) is obtained. To find the second order multipliers we start by the multiplier of the form,

\[ \xi = \xi(x,t,U,U_x,U_t,U_{xx},U_{tt},U_{xt}). \]

(15)

We can find \( \xi \) with the same expression such as (8), and (13). After tedious calculation we get second order conservation laws. The results are comming in table (3).
Similarity solution of the Zoomeron equation based on the vector fields (1). We make some discussion on the Zoomeron equation using Lie symmetries [3, 6, 7, 8].

### Classical similarity solutions

First of all, let us consider a one-parameter Lie group of infinitesimal transformation:

\[
\begin{align*}
x & \rightarrow x + \varepsilon \xi(x, t, u), \\
t & \rightarrow t + \varepsilon \tau(x, t, u), \\
u & \rightarrow u + \varepsilon \phi(x, t, u),
\end{align*}
\]

with a small parameter \(\varepsilon \ll 1\). The vector field associated with the above group of transformations can be written as

\[
X = \xi(x, t, u) \frac{\partial}{\partial x} + \tau(x, t, u) \frac{\partial}{\partial t} + \phi(x, t, u) \frac{\partial}{\partial u}. \tag{15}
\]

The symmetry group of Eq. (1) will be generated by the vector field of the form (15). Thus, this equation admits \(X\) as a symmetry operator if the condition

\[
X^{(4)}(1) \big|_{(1)} = 0,
\]

is satisfied on solutions of Eq (1). Applying the fourth prolongation and solving the determinining equation one can demonstrate the equation (1) admits the following Lie algebra:

\[
X_1 = \frac{\partial}{\partial t} + \frac{\partial}{\partial x}, \quad X_2 = \frac{\partial}{\partial x}, \quad X_3 = x \frac{\partial}{\partial x} + t \frac{\partial}{\partial t} - u \frac{\partial}{\partial u}. \tag{16}
\]

We make some discussion on the Zoomeron equation based on the vector fields (1).

### Similarity solution of \(X_1\)

For the generator \(X_1\), we have

\[
u = v(r, q), \tag{17}
\]

Table 3. Second Order Local Conservation Laws

<table>
<thead>
<tr>
<th>Fluxes</th>
<th>Density</th>
<th>Second Order Conservation Laws</th>
</tr>
</thead>
<tbody>
<tr>
<td>(xu_{xt} - ut + tu_{xt} + u_x)</td>
<td>(-xu_{xx} - tu_{xx})</td>
<td>(D_t(-xu_{xx} - tu_{xx}) + D_x(u_{xt} - tu_{xt} + u_x) = 0)</td>
</tr>
<tr>
<td>(u_xu_{tt} + u_tu_{xt})</td>
<td>(-ux_{xx} - u_{xx})</td>
<td>(D_t(-ux_{xx} - u_{xx}) + D_x(u_{xt} + u_{tt} + u_x) = 0)</td>
</tr>
<tr>
<td>(xu_{tt} + tu_{tt} + ut)</td>
<td>(-ux_{xx} - ut - tu_{xx})</td>
<td>(D_t(-ux_{xx} - ut - tu_{xx}) + D_x(u_{tt} + tu_{tt} + u_t) = 0)</td>
</tr>
<tr>
<td>(u_{xx} + u_xu_{t})</td>
<td>(-ux_{xx} - u_x^2)</td>
<td>(D_t(u_{xx} + u_xu_t) + D_x(-ux_{xx} - u_x^2) = 0)</td>
</tr>
<tr>
<td>(u_{tt} + u_t^2 - u_{xt})</td>
<td>(-ux_{xx} - u_{xx} + u_{tt})</td>
<td>(D_t(-ux_{xx} - u_{xx} + u_{tt}) + D_x(u_{tt} + u_t^2 - u_{xt}) = 0)</td>
</tr>
<tr>
<td>(xu_t + tu_t + u_t)</td>
<td>(-ux_x - u - tu_x)</td>
<td>(D_t(-ux_x - u - tu_x) + D_x(u_t + tu_t + u_t) = 0)</td>
</tr>
<tr>
<td>(x^2 + xt + t^2)</td>
<td>(-2xt - \frac{1}{2}t^2)</td>
<td>(D_t(-2xt - \frac{1}{2}t^2) + D_x(x^2 + xt + t^2) = 0)</td>
</tr>
<tr>
<td>(-ut - ut - u_t)</td>
<td>(ut_x + u_x + uu_x)</td>
<td>(D_t(u_{tx} + u_x + uu_x) + D_x(-ut_t - ut - uu_t) = 0)</td>
</tr>
<tr>
<td>(-x - xu_{tx} - u_{tt}u_t)</td>
<td>(t + uu_{xx} + uu_{xt})</td>
<td>(D_t(t + uu_{xx} + uu_{xt}) + D_x(-x - uu_{tx} - u_{tt}u_t) = 0)</td>
</tr>
</tbody>
</table>
where \( q = t, \ r = t - x \) are the group-invariants. Substituting (17) into (1), one can get

\[
-4v(r)^3 \left( \frac{d}{dr} v(r) \right)^2 + \left( \frac{d^2}{dr^2} v(r) \right) v(r) = 0. \tag{18}
\]

Consequently, the exact solution of (1) can be written as follows

\[
u(x,t) = \pm \sqrt{2a(t-x) + 2b}, \tag{19}\]

where \( a, b \) are arbitrary constants.

**Similarity solution of \( X_2 \)**

For the generator \( X_2 \), we have

\[
\exp(\epsilon X_2)(x,t,u) = (x + \epsilon, t, u), \tag{20}\]

with substituting \( \bar{x} = x + \epsilon \) and using (19), another exact solution of (1) can be written as follows

\[
u(x,t) = \pm \sqrt{2a(t-x - \epsilon) + 2b}. \tag{21}\]

**Similarity solution of \( X_3 \)**

For the generator \( X_3 \), we have

\[
\exp(\epsilon X_3)(x,t,u) = (e^\epsilon x, e^\epsilon t, e^{-\epsilon} u), \tag{22}\]

with substituting \( e^\epsilon x = \bar{x}, e^\epsilon t = \bar{t}, e^{-\epsilon} u = \bar{u} \) and using (19), another exact solution of (1) can be written as follows

\[
u(x,t) = \pm e^{-\epsilon} \sqrt{2a(e^{-\epsilon} t - e^{-\epsilon} x) + 2b}. \tag{23}\]

**Traveling wave solutions**

The most useful solution is the traveling wave solution associated with the space and time translation symmetries. Using the transformation

\[
u(x,t) = f(\xi), \quad \xi = x - ct \tag{24}\]

and substituting the expression (1) into (1) yields,

\[
-c^3 \left( \frac{-f''}{f} \right)'' + c \left( \frac{f''}{f} \right)'' - 2c \left( f^2 \right)'' = 0. \tag{25}\]

With integrating twice with respect to \( \xi \), by setting the second integration constant equal to zero, we obtain the following non-linear ordinary differential equation

\[
-c^3 f'' + cf'' - 2cf^3 - Rf = 0, \tag{26}\]
where \( R \) is integration constant.

So the solutions of Zoomeron equation can be obtained by (27),

\[
\begin{align*}
    u(x,t) &= c_2 \sqrt{-\frac{R}{c_2^2 c - c - R}} \text{JacobiSN} \left( \left( \frac{\sqrt{c(c^2 - 1)(c+R)(x-ct)}}{c(c^2 - 1)} + c_1 \right) \sqrt{-\frac{R}{c_2^2 c - c - R}} \right),
\end{align*}
\]

(27)

where \( c_2, c_1 \) are arbitrary constants and JacobiSN is an elliptic function.

**Conclusion**

In this paper we introduced a Lie group analysis for an important PDEs called Zoomeron equation. The Lie algebra of symmetries was found by a useful algorithm. We used the direct method to obtain fluxes and densities of conservation laws for the equation. Finally we used the symmetries to find the reduction forms of the Zoomeron equation.

**References**


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